

# Conditional Independence, Dependency-Separation, and Bayesian Networks

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Consider three variables  $a$ ,  $b$ , and  $c$ , and suppose that the conditional distribution of  $a$  given  $b$  and  $c$  is such that it does not depend on the value of  $b$  [i.e.,  $p(a|b, c) = p(a|c)$ ]. In this case,  $a$  is conditionally independent of  $b$  given  $c$ . This can be expressed in a slightly different way by considering the joint distribution of  $a$  and  $b$  given  $c$ , which can be written as follows:

$$p(a, b|c) = p(a|b, c)p(b|c) \tag{1}$$

$$= p(a|c)p(b|c) \tag{2}$$

Note that our definition of conditional independence requires that this equation holds for every possible value of  $c$ , and not just for some values.

Consider the Bayesian network in Figure 1. Based on this graph, we can write the joint distribution of  $a$  and  $b$  given  $c$  as follows:

$$p(a, b|c) = \frac{p(a, b, c)}{p(c)} \tag{3}$$

$$= p(a|c)p(b|c) \tag{4}$$

meaning that  $a$  and  $b$  are conditionally independent given  $c$ . We can provide a simple graphical interpretation of this result by considering the path from  $a$  to  $b$  via  $c$ . Node  $c$  is said to be “tail-to-tail” with respect to this path because the node is connected to the tails of the two arrows. When  $c$  is unobserved, the presence of this path causes  $a$  and  $b$  to be dependent. However, when  $c$  is observed and we condition on  $c$ , then the conditioned node “blocks” the path from  $a$  to  $b$  and causes  $a$  and  $b$  to become conditionally independent.

Now consider the network in Figure 2. Based on this graph, the joint distribution of  $a$  and  $b$  given  $c$  is:

$$p(a, b|c) = \frac{p(a, b, c)}{p(c)} \tag{5}$$

$$= p(a)p(c|a)p(b|c) \tag{6}$$

$$= p(a|c)p(b|c) \tag{7}$$

meaning that, again,  $a$  and  $b$  are conditionally independent given  $c$ . The node  $c$  is said to be “head-to-tail” with respect to the path from  $a$  to  $b$ . If  $c$  is unobserved, then such a path connects  $a$  and  $b$  and renders them dependent. But if  $c$  is observed, then this observation “blocks” the path, and  $a$  and  $b$  become conditionally independent.

Lastly, consider the networks in Figure 3. First, we consider the case when node  $c$  is unobserved (left graph). In this case  $a$  and  $b$  are independent. Next, we consider the case when  $c$  is observed (right graph). Based on this graph, the joint distribution of  $a$  and  $b$  given  $c$  is:

$$p(a, b|c) = \frac{p(a, b, c)}{p(c)} \tag{8}$$

$$= \frac{p(a)p(b)p(c|a, b)}{p(c)} \tag{9}$$

which does not factorize into the product  $p(a|c)p(b|c)$  meaning that  $a$  and  $b$  are not conditionally independent given  $c$ . Graphically, we say that node  $c$  is “head-to-head” with respect to the path from  $a$  to  $b$  because it connects to the heads of the two arrows. When  $c$  is unobserved, it “blocks” the path, and the variables  $a$  and  $b$  are independent. However, conditioning on  $c$  unblocks the path and renders  $a$  and  $b$  dependent. There is one more subtlety to this third example. As a matter of terminology, a node  $y$  is a descendent of a node  $x$  if there is a path from  $x$  to  $y$  in which each step of the path follows the directions of the arrows. Then it can be shown that a head-to-head path becomes unblocked if either the node or any of its descendants is observed.

In the graphical models literature, people talk about the d-separation property for directed graphs. Consider a general directed graph in which  $A$ ,  $B$ , and  $C$  are arbitrary nonintersecting sets of nodes (whose union may be smaller than the complete set of nodes in the graph). We want to know if  $A$  and  $B$  are conditionally independent given  $C$ . To determine this, we consider all possible paths from any node in  $A$  to any node in  $B$ . Any such path is said to be blocked if it includes a node such that either:

- the arrows on the path meet either head-to-tail or tail-to-tail at the node, and the node is in the set  $C$ , or
- the arrows meet head-to-head at the node, and neither the node nor any of its descendants is in  $C$ .

If all paths are blocked, then  $A$  is d-separated from  $B$  by  $C$ .

Consider the graphs in Figure 4. In the left graph, the path from  $a$  to  $b$  is not blocked by  $f$  because it is a tail-to-tail node for this path and it is not observed, nor is it blocked by node  $e$  because, although the latter is a head-to-head node, it has a descendant  $c$  which is in the conditioning set. Thus,  $a$  and  $b$  are not conditionally independent given  $c$ . In the right graph, the path from  $a$  to  $b$  is blocked by node  $f$  because this is a tail-to-tail node that is observed, meaning that  $a$  and  $b$  are conditionally independent given  $f$ . In addition, this path is also blocked by  $e$  because  $e$  is a head-to-head node and neither it nor its descendants are in the conditioning set.

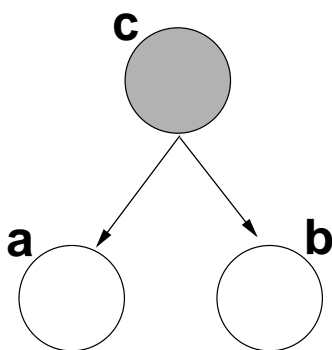


Figure 1: Node  $c$  is a parent of  $a$  and  $b$ . The value of  $c$  is observed.

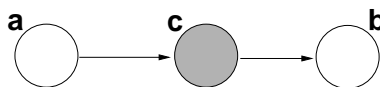


Figure 2: Node  $a$  is a parent of  $c$  which, in turn, is a parent of  $b$ . The value of  $c$  is observed.

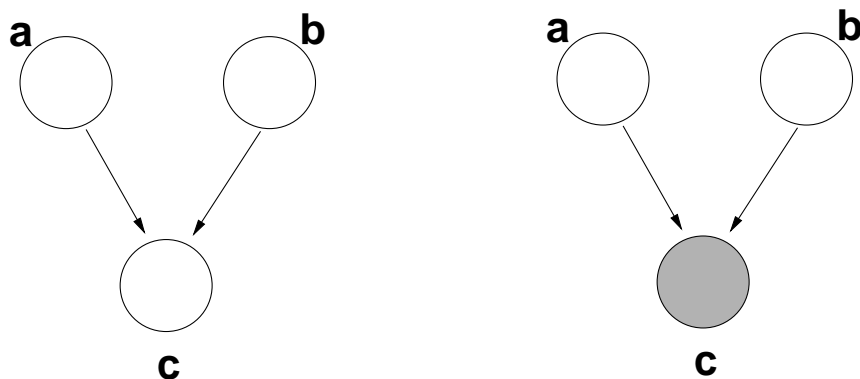


Figure 3: Nodes  $a$  and  $b$  are parents of  $c$ . In the left graph, the value of  $c$  is unobserved. In the right graph, it is observed.

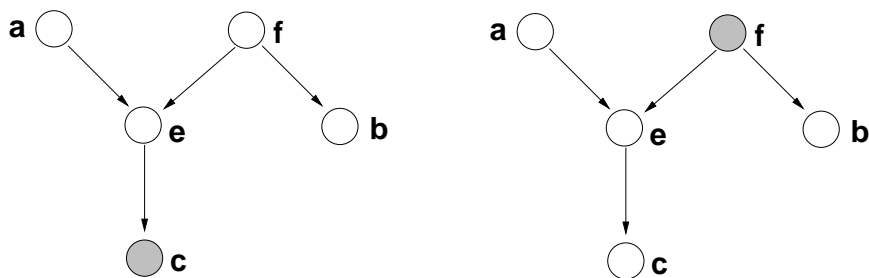


Figure 4: Graphs referred to in text.