

DISCOVERING VOXEL-LEVEL FUNCTIONAL CONNECTIVITY BETWEEN CORTICAL REGIONS

C. BALDASSANO



M.C. IORDAN



D.M. BECK

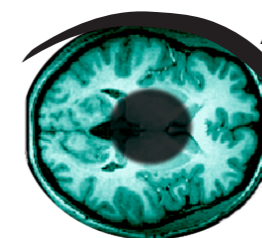


L. FEI-FEI



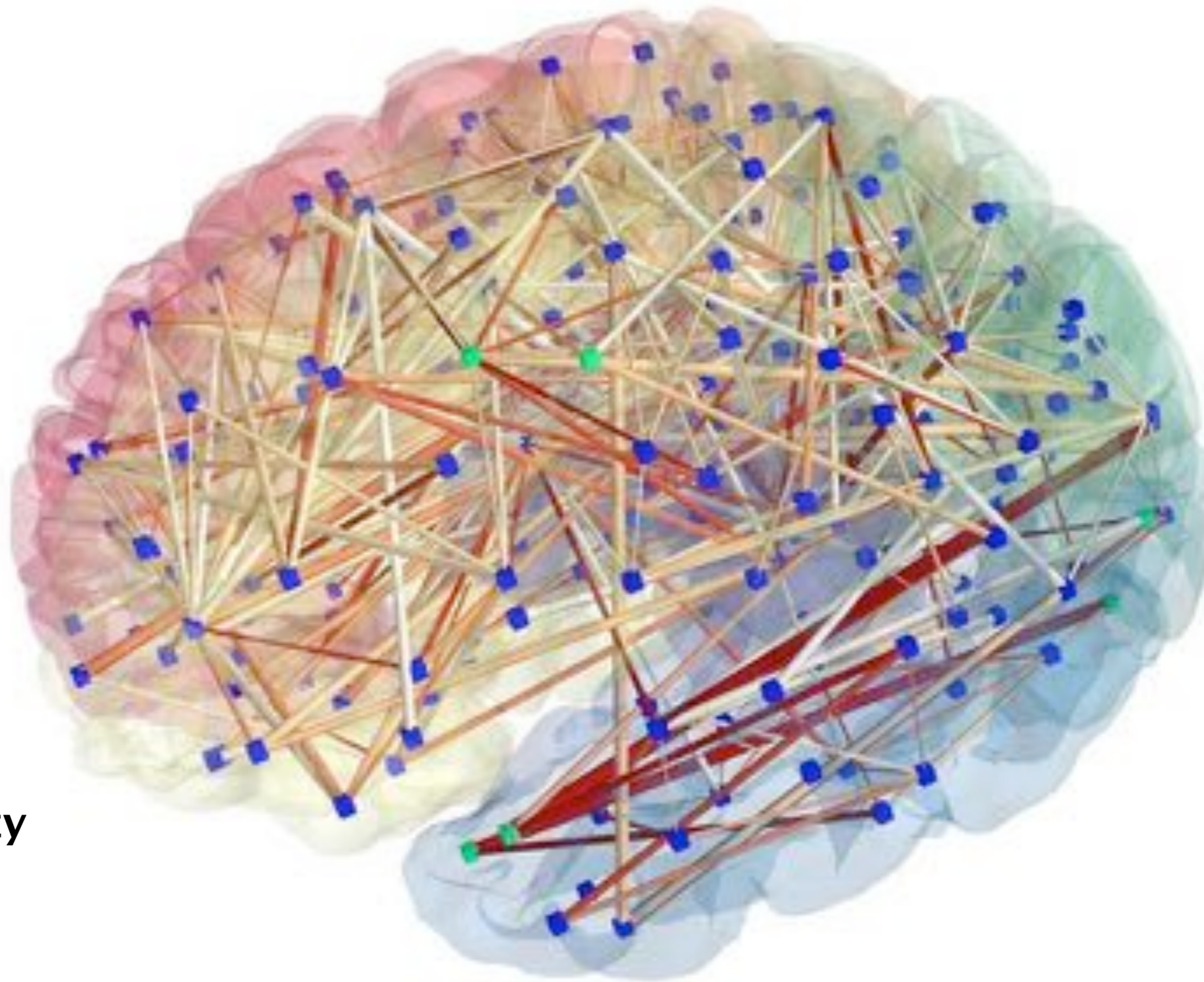
Computer Science Department, Stanford University

Beckman Institute and Psychology Department, University of Illinois at Urbana-Champaign



*Attention and
Perception Lab*

Connectivity



Subregion Connectivity

Precuneus
Amygdala
Thalamus
Lateral occipital complex LOC

Zhang et al. 2008
Kim et al. 2010
Roy et al. 2009
Margulies et al. 2007
Margulies et al. 2009
Heinze & Haynes 2011



GOAL: Fine-Grained Connectivity

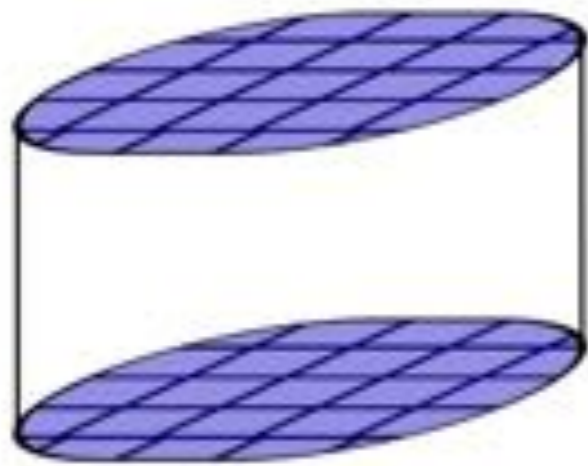
Voxel-level Maps
Symmetrical
Few Data Points Needed

Subregion Connectivity

Precuneus
Amygdala
Thalamus
Lateral occipital complex LOC

Zhang et al. 2008
Kim et al. 2010
Roy et al. 2009
Margulies et al. 2007
Margulies et al. 2009
Heinzle & Haynes 2011

Area 1

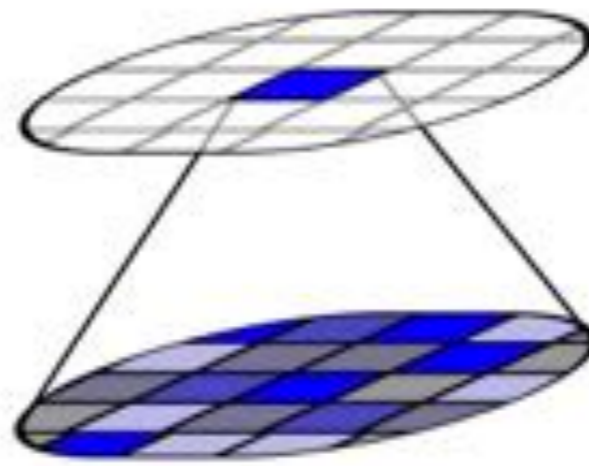


Area 2

Traditional

no voxel-level connectivity
cannot identify novel subregions

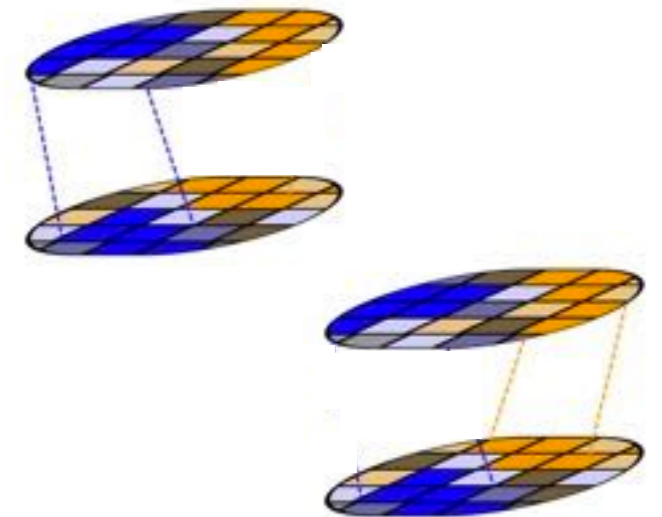
Rogers et al. 2007



CCRF / FF

treats areas asymmetrically
no continuous maps
post-hoc clustering often needed

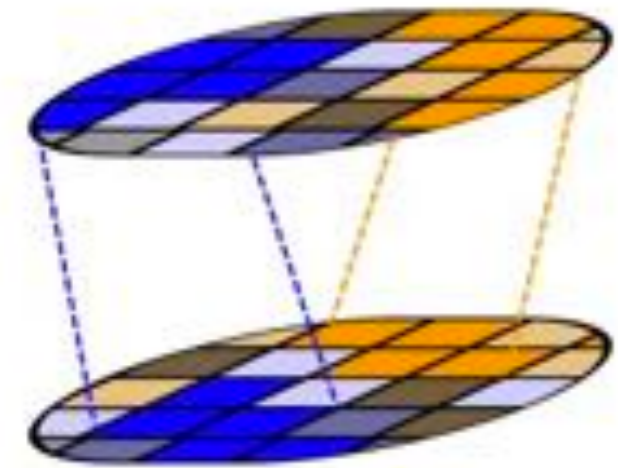
Kim et al. 2010
Margulies et al. 2007
Margulies et al. 2009
Haak et al. 2011
Cohen et al. 2007



CCA

voxels < # timepoints
cannot identify multiple correlated correspondences

Deleus & Van Hulle 2011



Our Method:
Jointly Learn Continuous Maps over 2 Areas
Multiple Solutions, Even If Correlated

Traditional

no voxel-level connectivity
cannot identify novel subregions

Rogers et al. 2007

CCRF / FF

treats areas asymmetrically
no continuous maps
post-hoc clustering often needed

Kim et al. 2010
Margulies et al. 2007
Margulies et al. 2009
Haak et al. 2011
Cohen et al. 2007

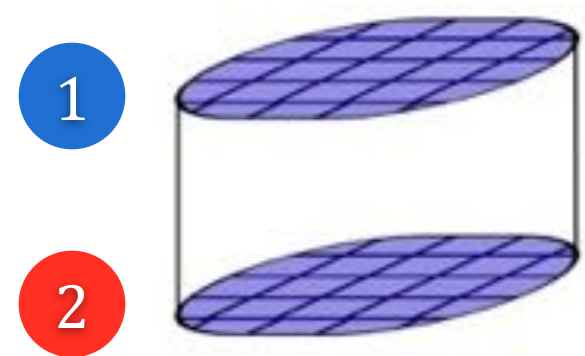
CCA

voxels < # timepoints
cannot identify multiple correlated correspondences

Deleus & Van Hulle 2011

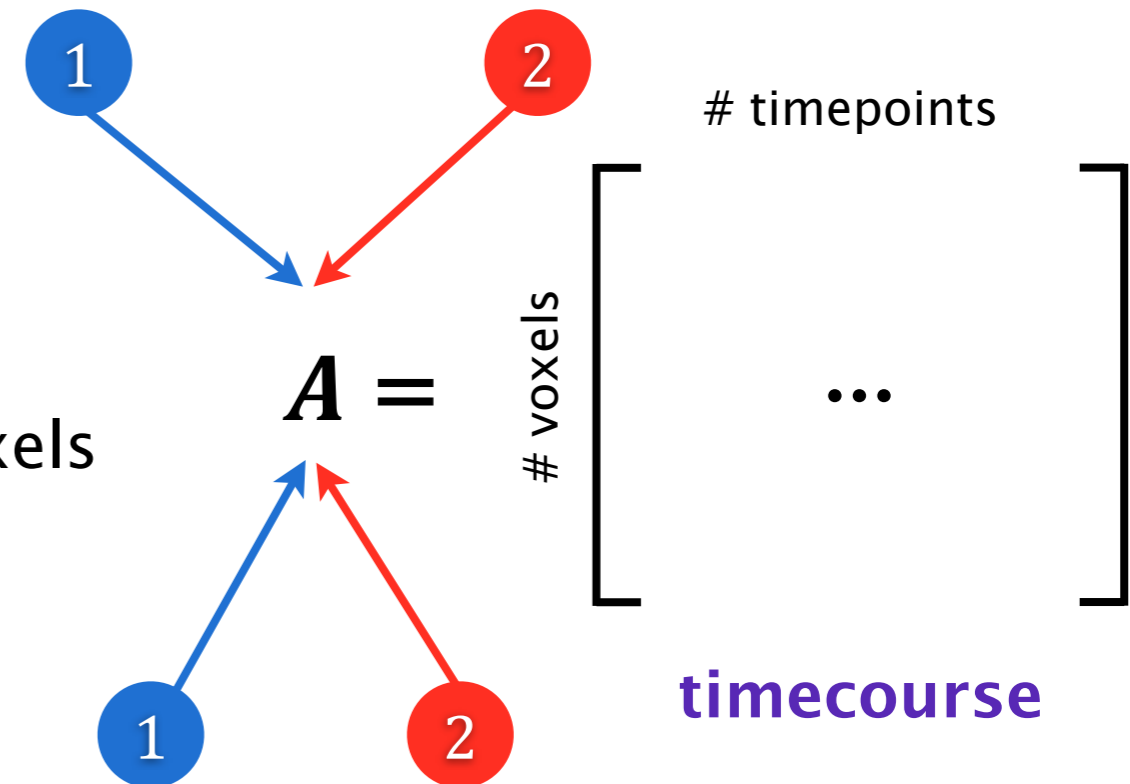
Optimization Problem

Traditional



$$\underset{w}{\text{minimize}} \quad \|w \cdot \text{mean}_v(\mathbf{A}^1) - \text{mean}_v(\mathbf{A}^2)\|_2^2$$

w \longrightarrow scalar
 mean_v \longrightarrow mean across voxels



$$\underset{a^1, a^2, w}{\text{minimize}}$$

$$\|a^{1T} \mathbf{A}^1 - a^{2T} \mathbf{A}^2\|_2^2$$

subject to

$$a^1 = \frac{w}{N_{A^1}} \cdot \mathbf{1}, \quad a^2 = \frac{1}{N_{A^2}} \cdot \mathbf{1}$$

constant connectivity map

$$a^T = \begin{bmatrix} \dots \\ N_A \text{ voxels} \end{bmatrix}$$

Optimization Problem

Traditional

constant map

minimize
 $\mathbf{a}^1, \mathbf{a}^2, w$

subject to

$$\|\mathbf{a}^{1T} \mathbf{A}^1 - \mathbf{a}^{2T} \mathbf{A}^2\|_2^2$$

$$\mathbf{a}^1 = \frac{w}{N_{A^1}} \cdot \mathbf{1}, \quad \mathbf{a}^2 = \frac{1}{N_{A^2}} \cdot \mathbf{1}$$

CCRF / FF

**one non-constant
connectivity maps**

minimize
 $\mathbf{a}^1, \mathbf{a}^2, w$

subject to

$$\|\mathbf{a}^{1T} \mathbf{A}^1 - \mathbf{a}^{2T} \mathbf{A}^2\|_2^2$$

$$\mathbf{a}^1 = \frac{w}{N_{A^1}} \cdot \mathbf{1}, \quad \mathbf{a}^2 = \frac{1}{N_{A^2}} \cdot \mathbf{1}$$

Our Method

**two non-constant
connectivity maps**

minimize
 $\mathbf{a}^1, \mathbf{a}^2, w$

subject to

$$\|\mathbf{a}^{1T} \mathbf{A}^1 - \mathbf{a}^{2T} \mathbf{A}^2\|_2^2$$

$$\mathbf{a}^1 = \frac{w}{N_{A^1}} \cdot \mathbf{1}, \quad \mathbf{a}^2 = \frac{1}{N_{A^2}} \cdot \mathbf{1}$$

Optimization Problem

minimize
 $\mathbf{a}^1, \mathbf{a}^2, w$

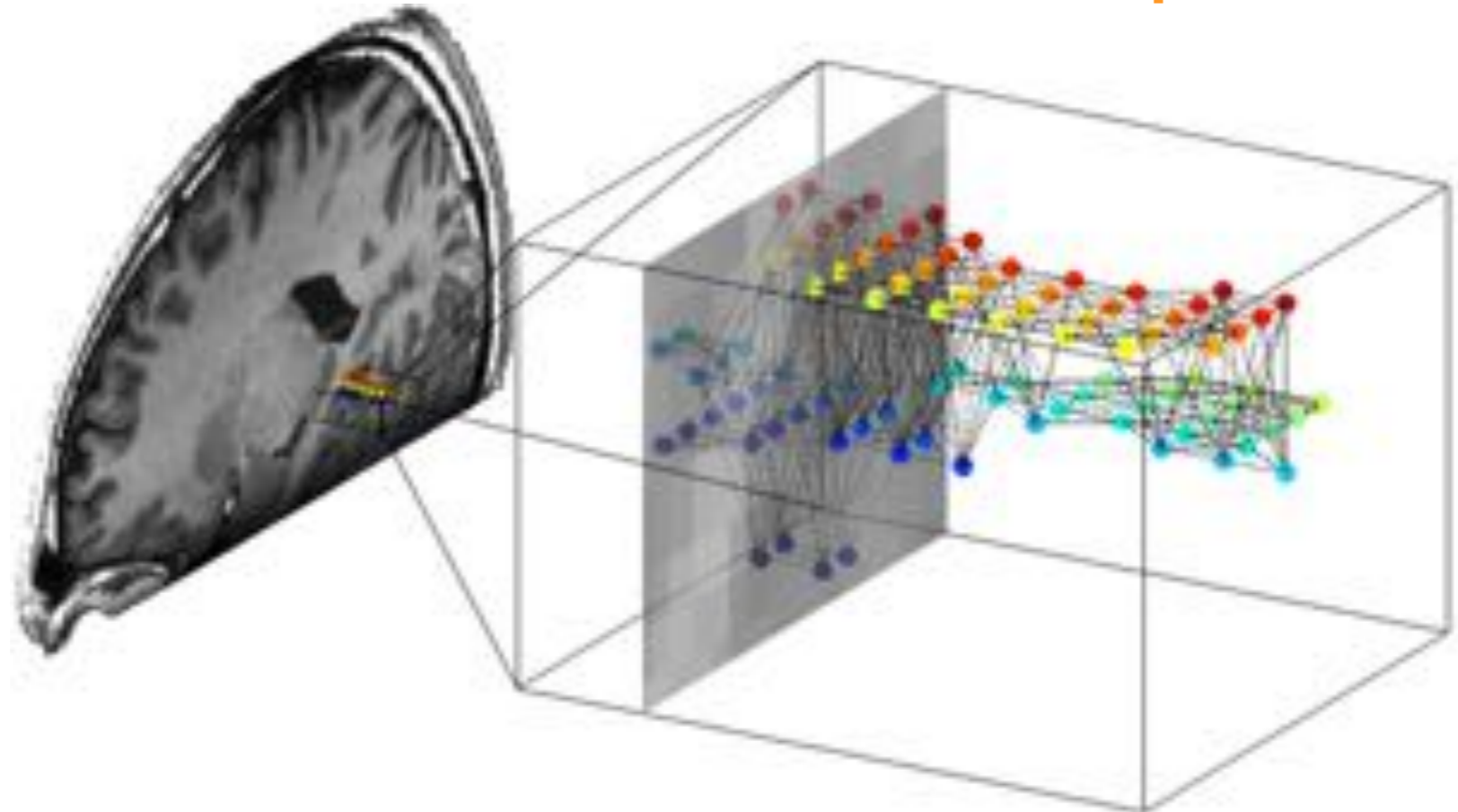
Hyperparameter

Regularization term

$$\|\mathbf{a}^{1T} \mathbf{A}^1 - \mathbf{a}^{2T} \mathbf{A}^2\|_2^2 + \lambda \left[\sum_{i \in v_1} \sum_{j \in n(i)} \frac{1}{|n(i)|} (\mathbf{a}_i^1 - \mathbf{a}_j^1)^2 + \sum_{i \in v_2} \sum_{j \in n(i)} \frac{1}{|n(i)|} (\mathbf{a}_i^2 - \mathbf{a}_j^2)^2 \right]$$

Graph D_k

Sparse
Connectivity
Graph



Optimization Problem

minimize
 a^1, a^2, w

Hyperparameter

Regularization term

$$\|a^{1T} A^1 - a^{2T} A^2\|_2^2 + \lambda \left[\sum_{i \in v_1} \sum_{j \in n(i)} \frac{1}{|n(i)|} (a_i^1 - a_j^1)^2 + \sum_{i \in v_2} \sum_{j \in n(i)} \frac{1}{|n(i)|} (a_i^2 - a_j^2)^2 \right]$$

minimize
 a^1, a^2, w

$$\left\| \begin{bmatrix} \frac{1}{\sqrt{T}} A^{1T} & -\frac{1}{\sqrt{T}} A^{2T} \\ \sqrt{\lambda} D_1 & 0 \\ 0 & \sqrt{\lambda} D_2 \end{bmatrix} \begin{bmatrix} a^1 \\ a^2 \end{bmatrix} \right\|_2^2 = \|X_\lambda \cdot \beta\|_2^2$$

minimize
 β

$$\|X_\lambda \cdot \beta\|_2^2$$

subject to

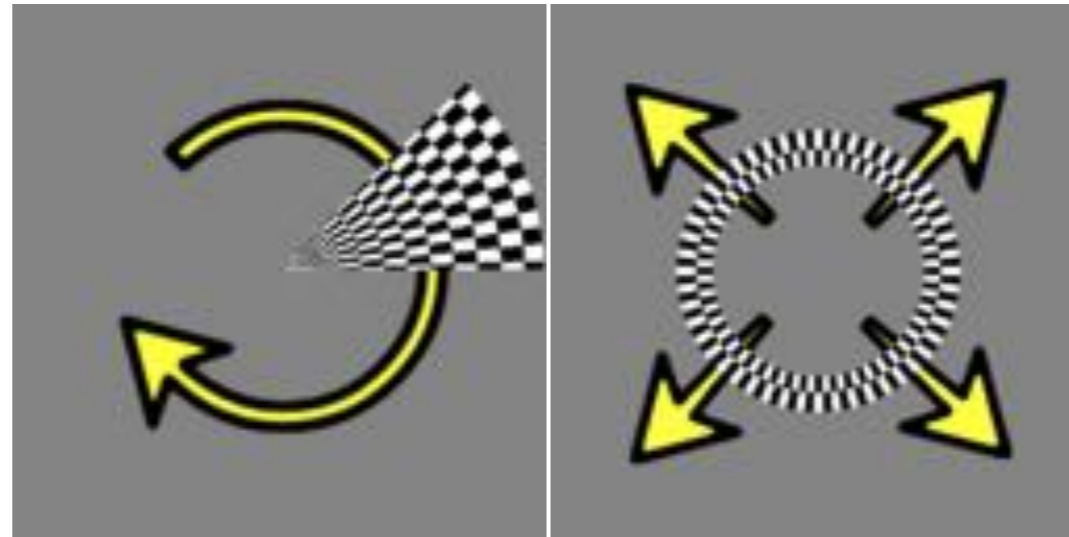
$$\|\beta\|_2 = 1, \beta \succeq 0$$

Not Convex

Use trust region approach and multiple initializations

Our Method

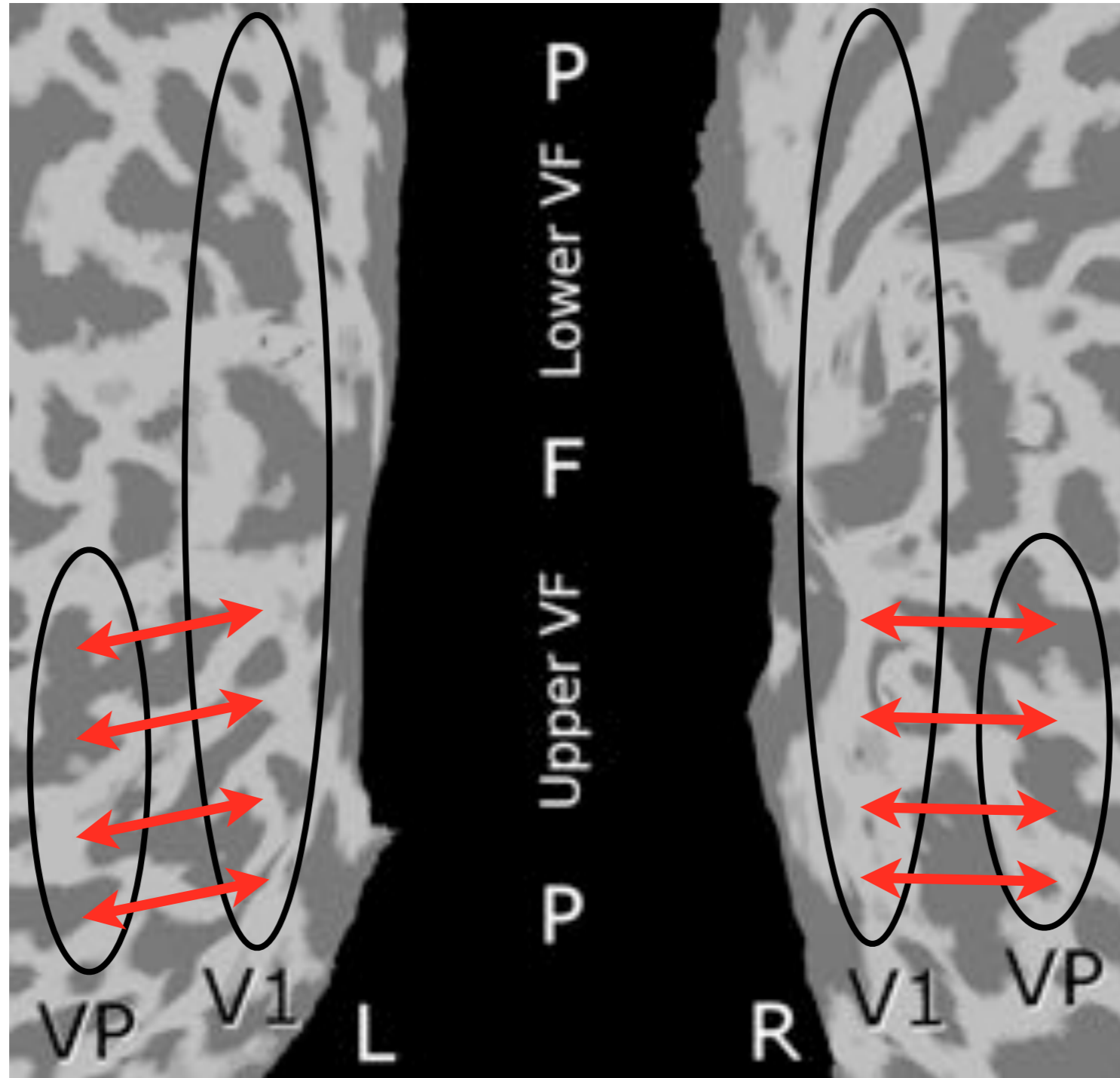
Meridian and Eccentricity Mapping 256 timepoints



Isolated Objects & Objects in Context 306 timepoints

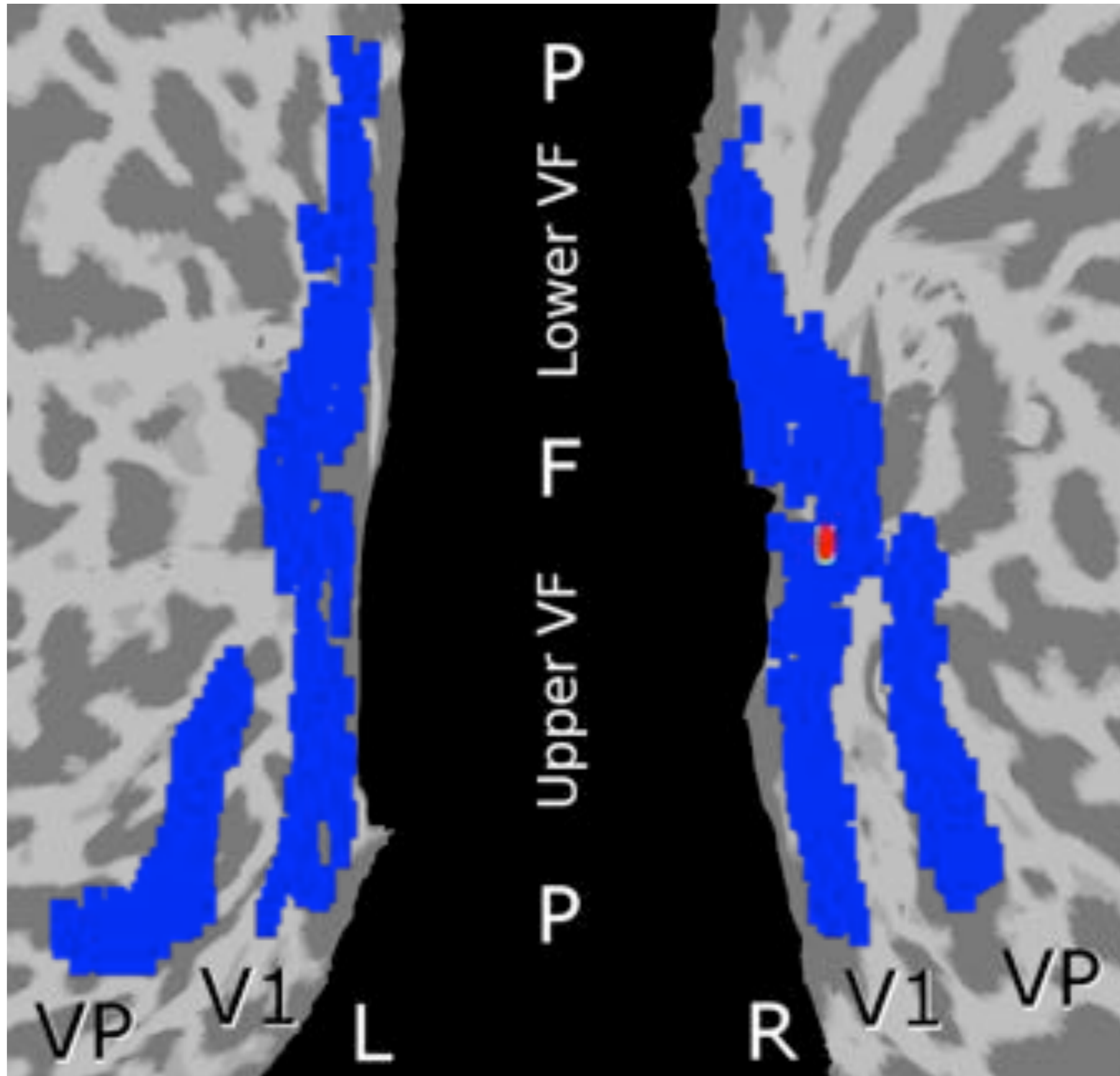


V1 - VP Connectivity

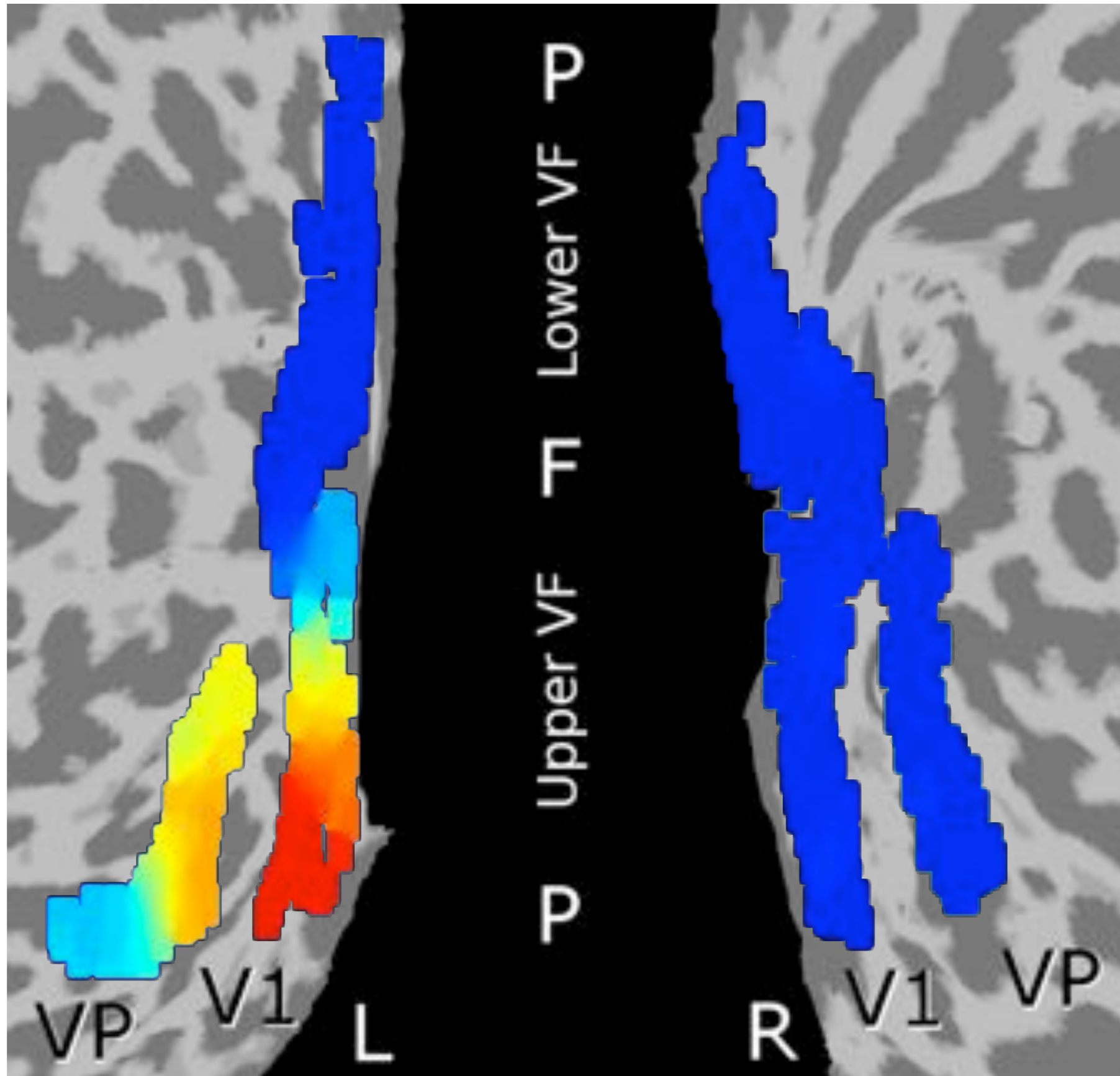


Expected Connectivity

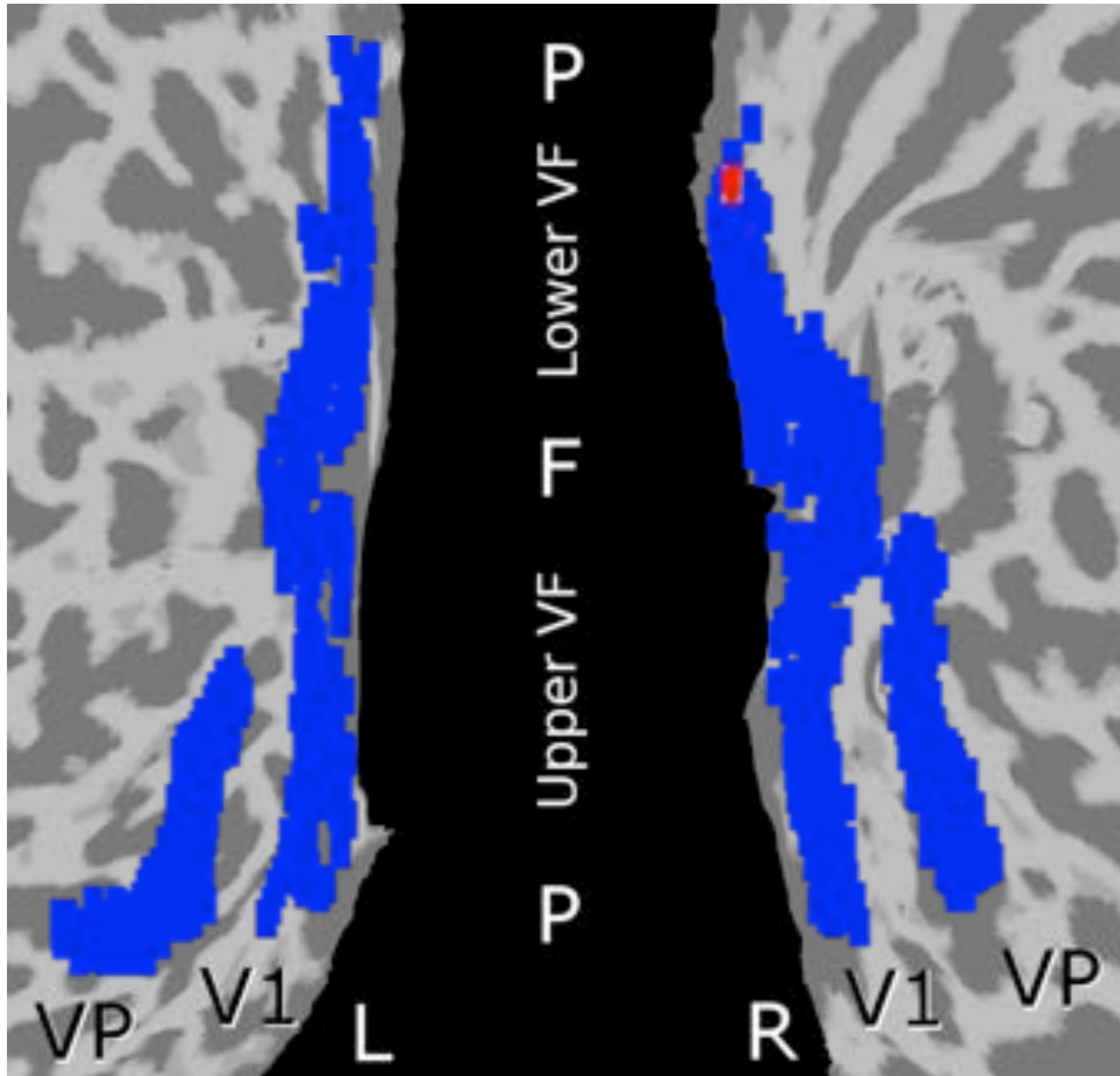
V1 - VP Connectivity



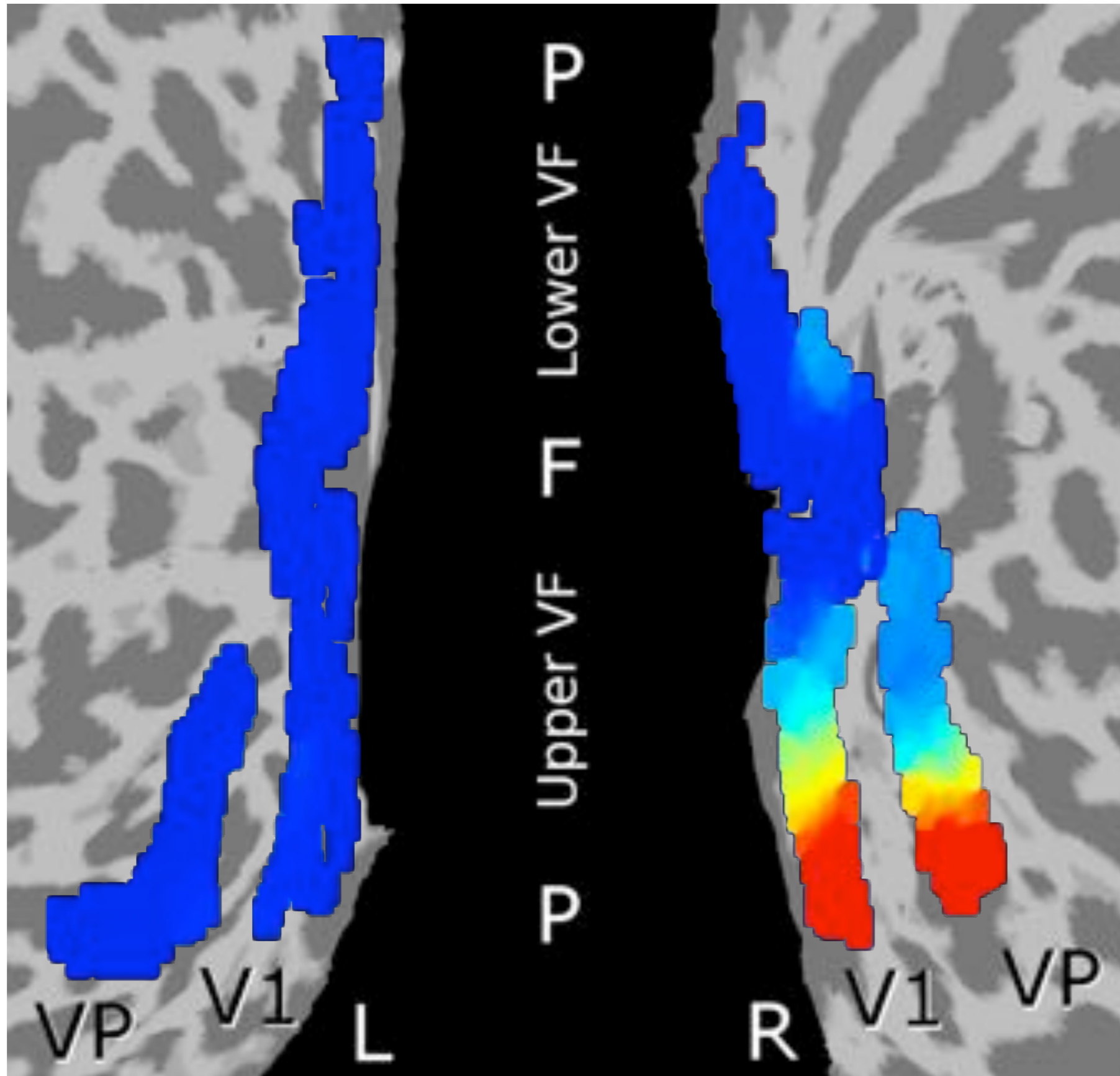
V1 - VP Connectivity



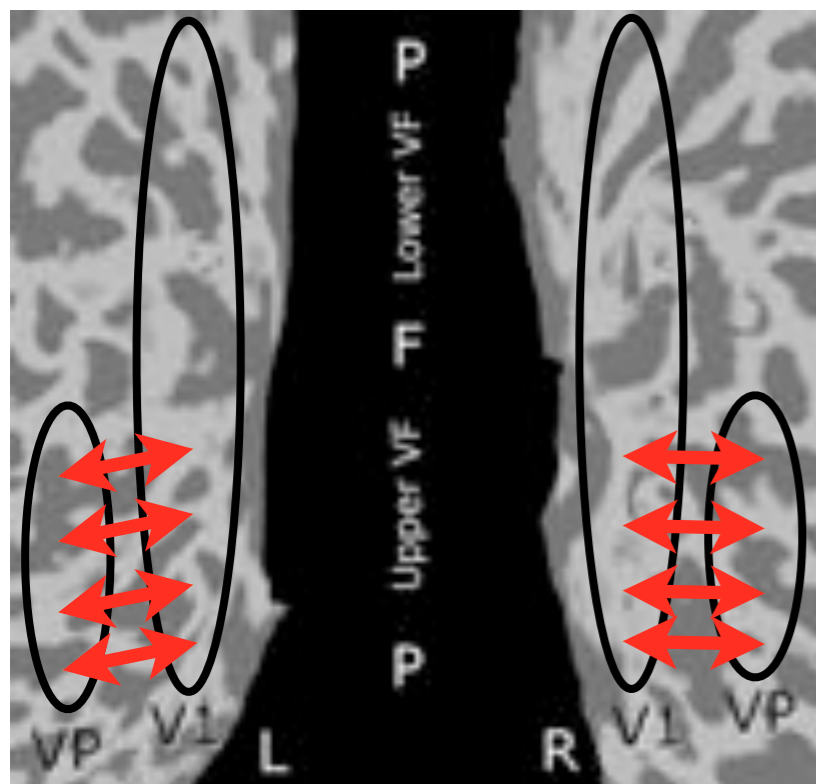
V1 - VP Connectivity



V1 - VP Connectivity

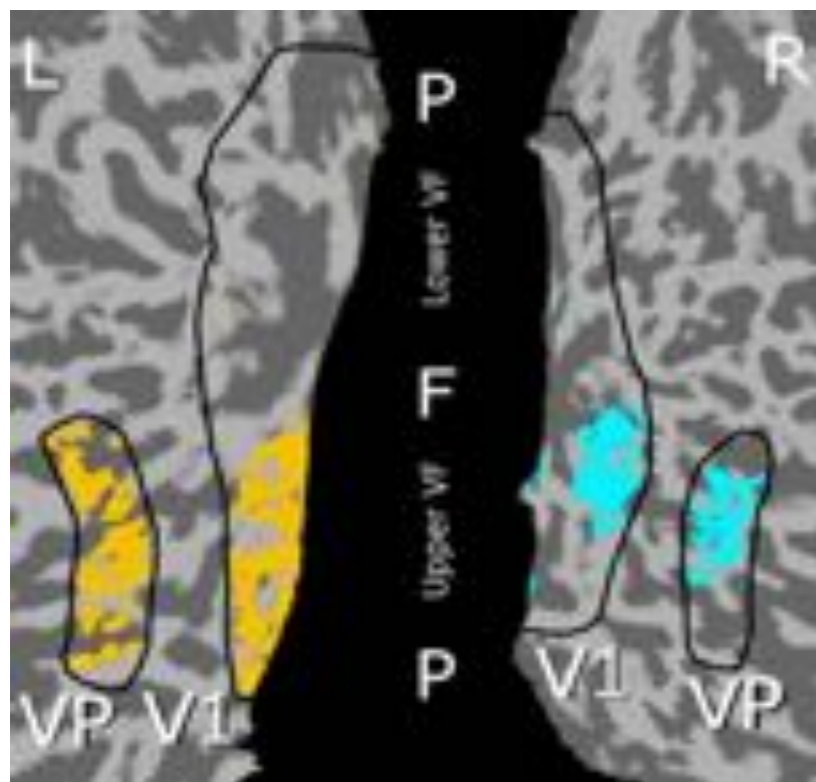


V1 - VP Connectivity



Expected Connectivity

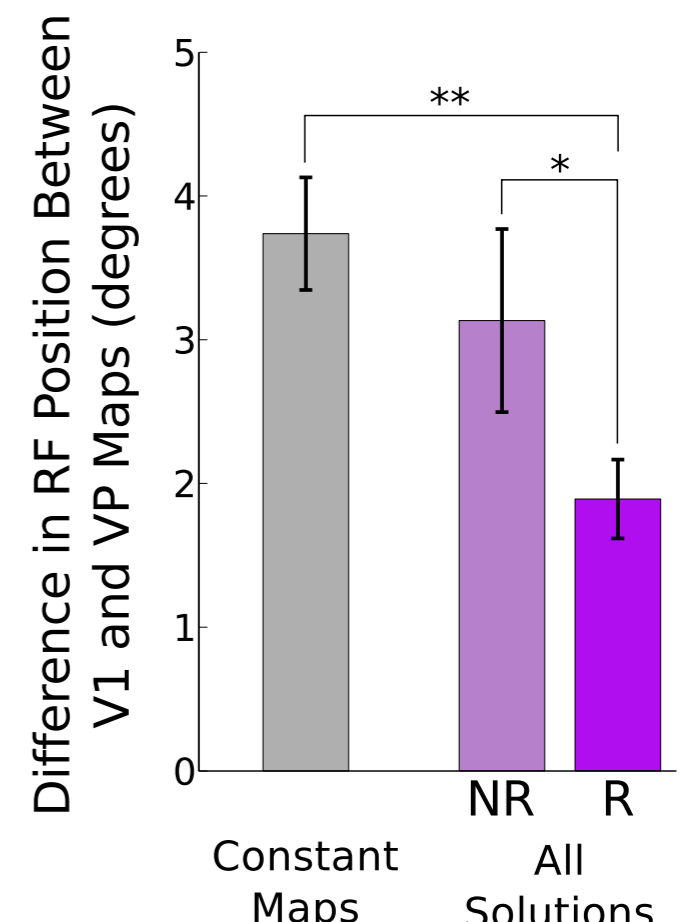
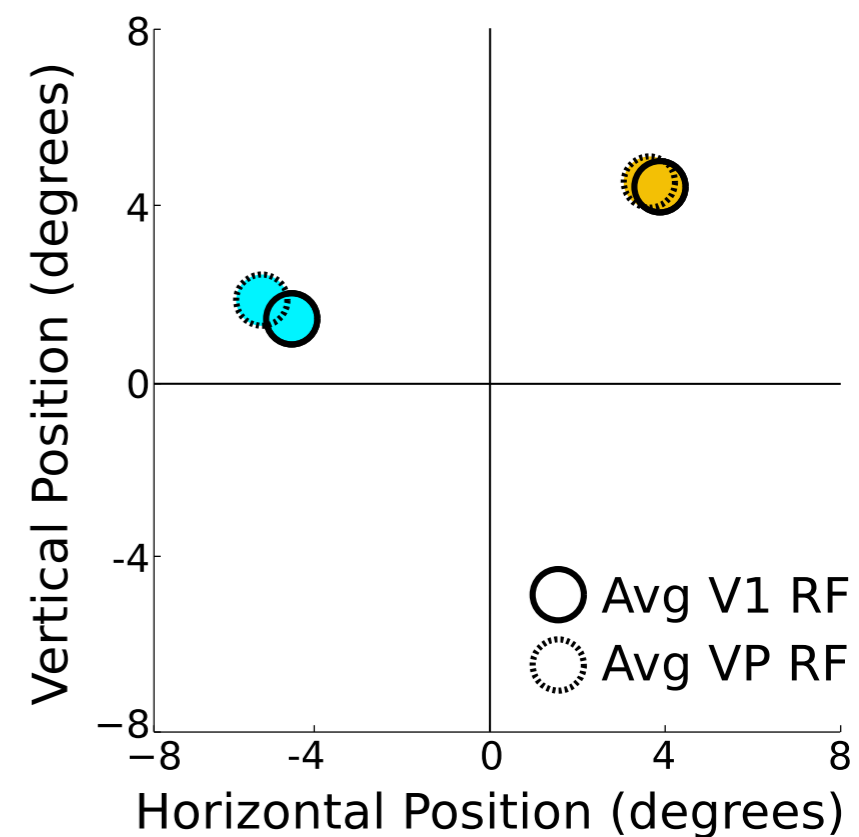
Solutions Found



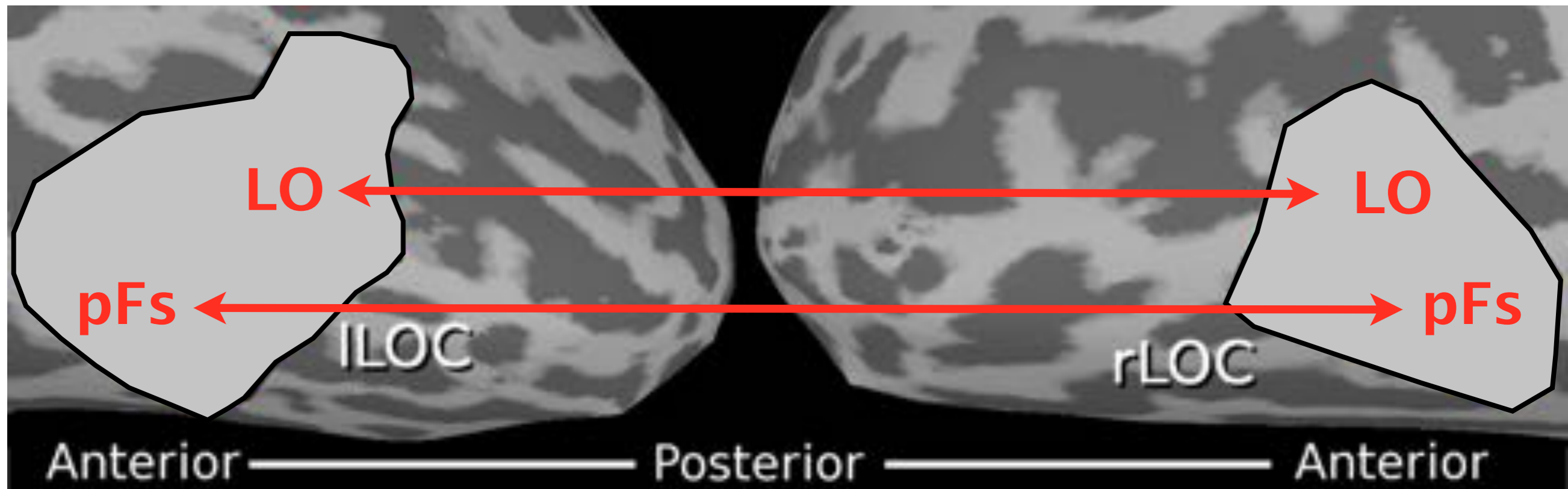
Solution Maps Consistent with Retinotopic Organization

Regularization Improves RF Localization

256 Timepoints

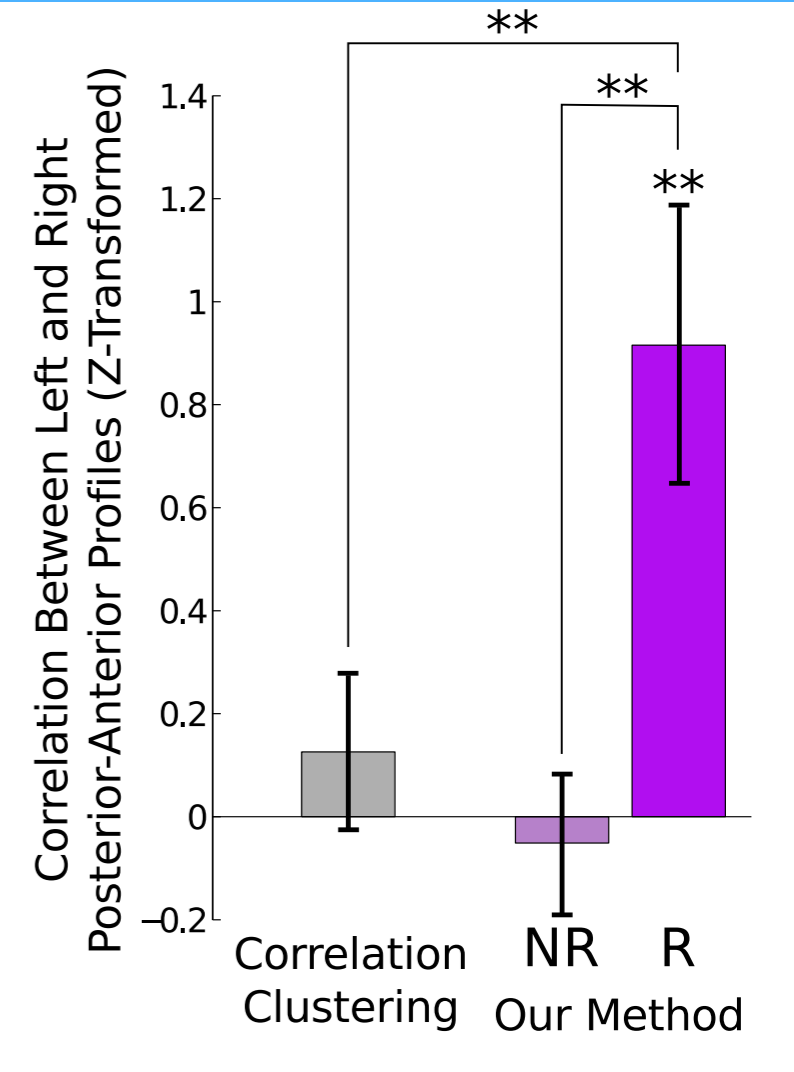
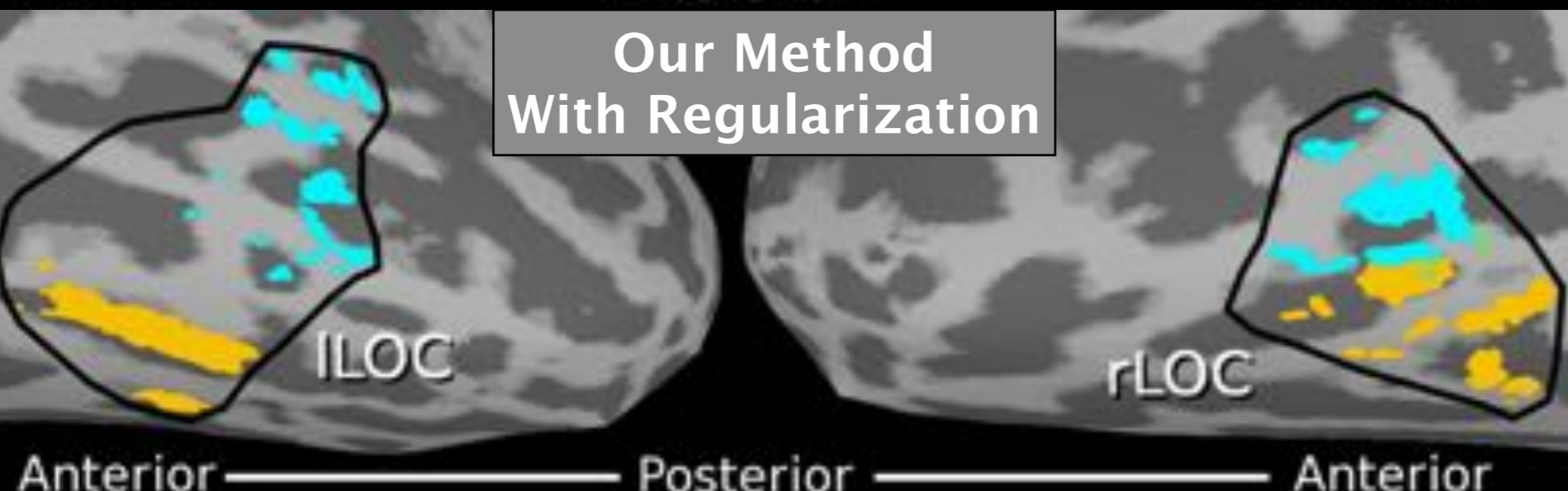
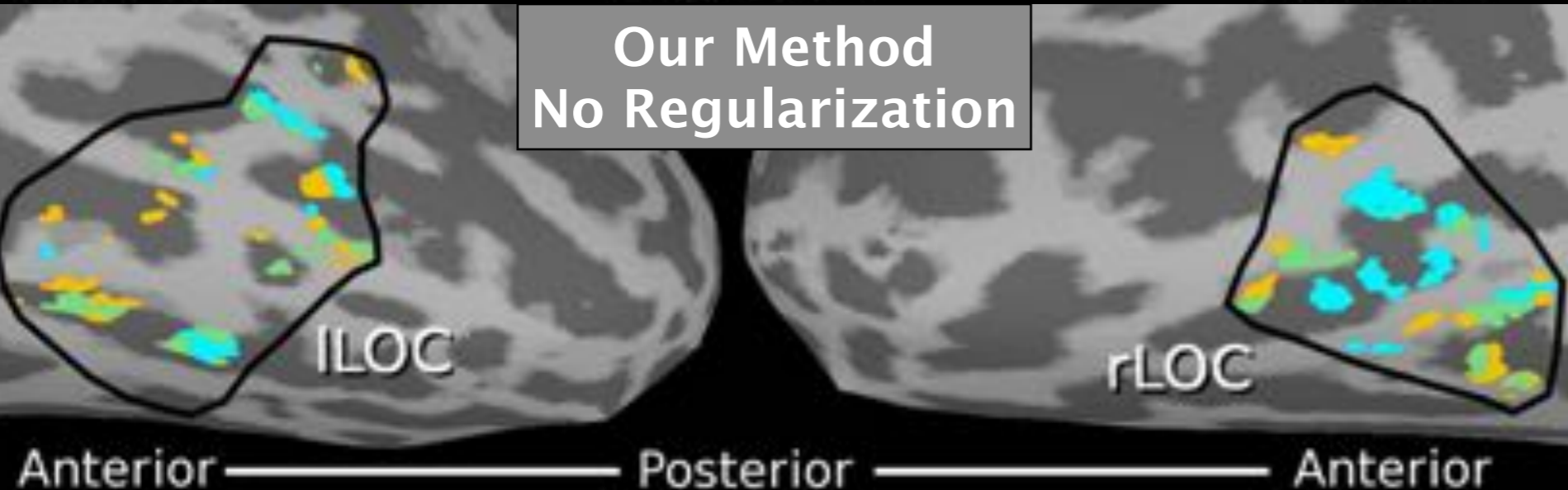
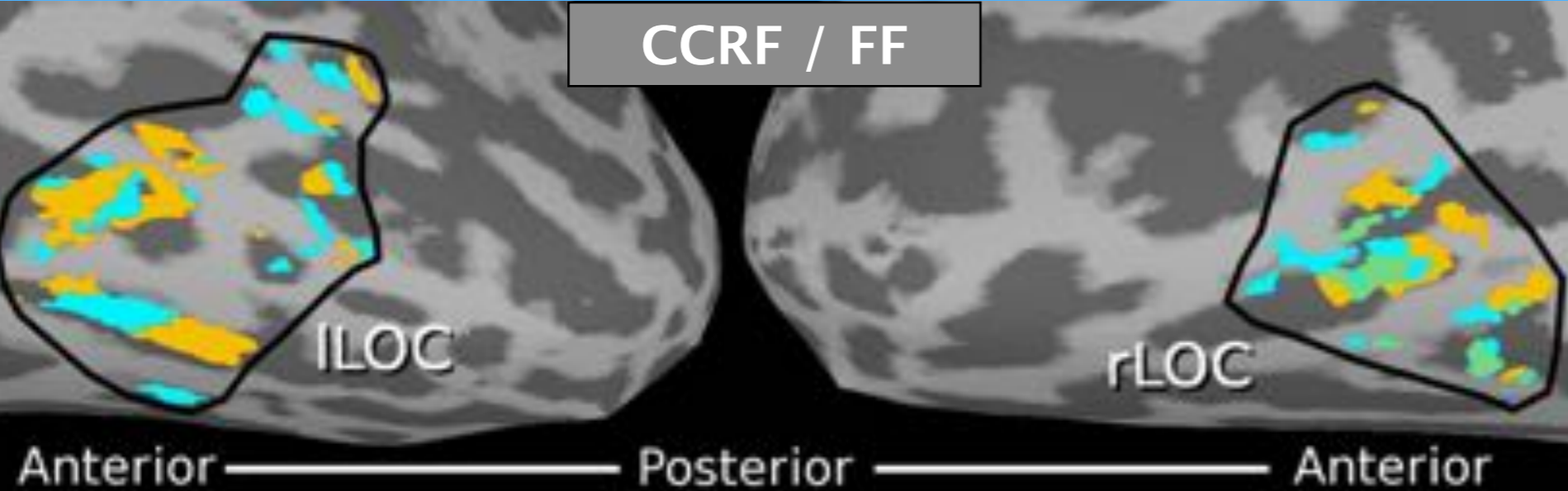


Left LOC – Right LOC Connectivity



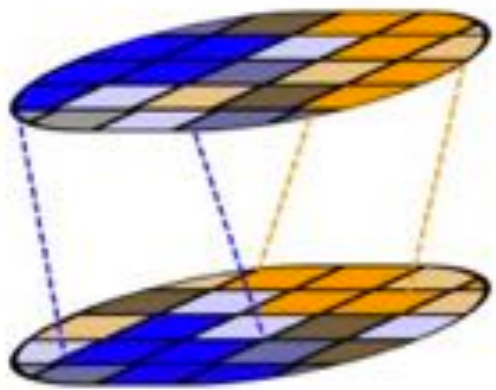
Expected Connectivity

Left LOC – Right LOC Connectivity

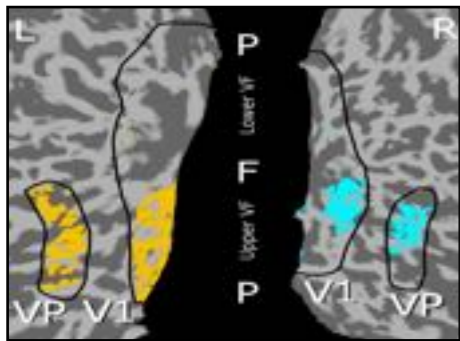


Regularized Method Recovers Anterior-Posterior Connectivity

Timecourse Correlation $r = 0.8$



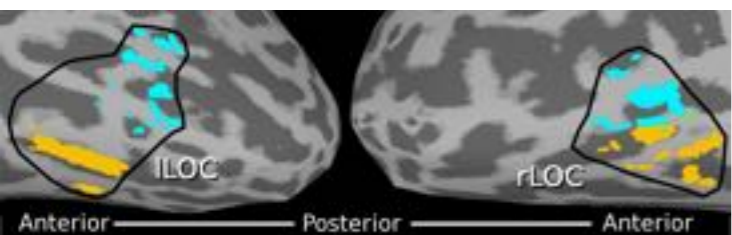
Jointly Learns Continuous Connectivity Maps



Can Recover Retinotopic Organization and Anterior-Posterior Differences in LOC



No Specialized Datasets,
Fewer Timepoints than Voxels!



Can Recover Correlated Distinct Solutions

Implementation Available at:
vision.stanford.edu/resources_links.html

C. BALDASSANO

M.C. IORDAN

D.M. BECK

L. FEI-FEI



MCI@STANFORD.EDU

CHRISB33@STANFORD.EDU

Acknowledgements: NSF, SGF, NIH